

Checking Two Structural Properties of Vector Addition Systems with States

Florent Avellaneda & Rémi Morin

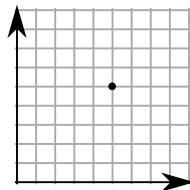
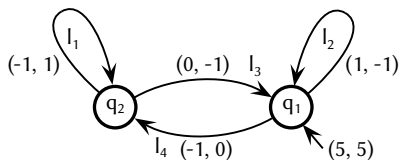
Université d'Aix Marseille

6 décembre 2012

Definition

A *vector addition system with state (VASS)* is a directed graph $G = (Q, A, i)$ with :

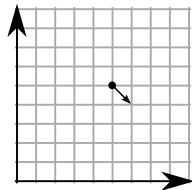
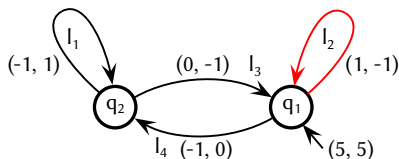
- Q a finite set of nodes.
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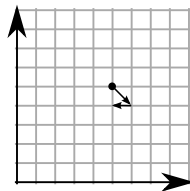
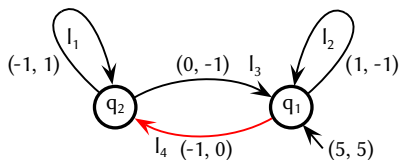
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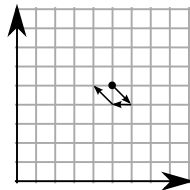
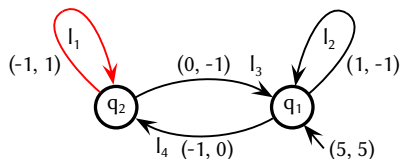
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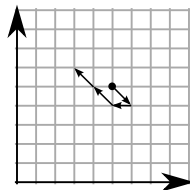
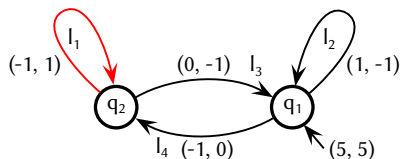
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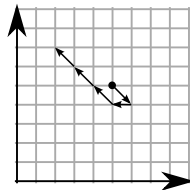
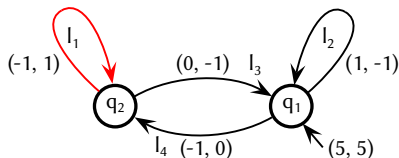
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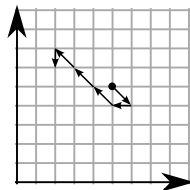
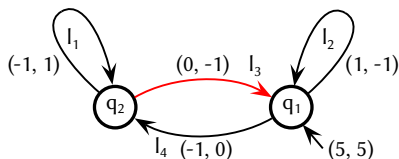
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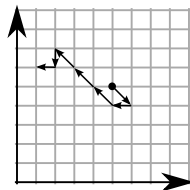
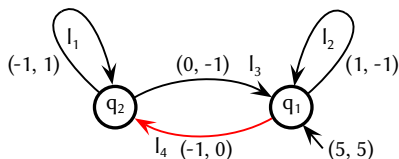
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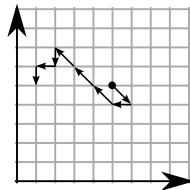
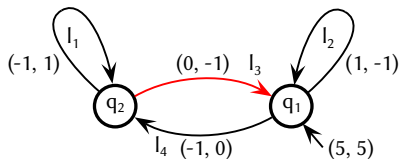
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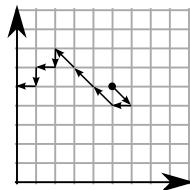
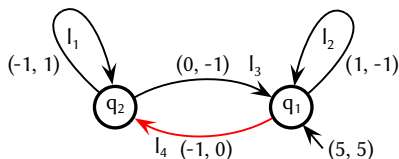
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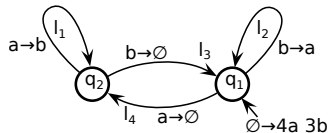
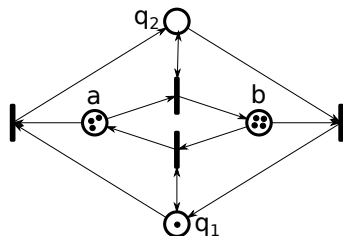
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Petri net

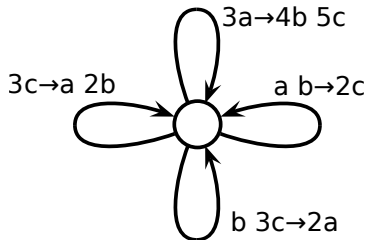
VASS are very close to Petri nets :

- A VASS can be simulated by a Petri net.



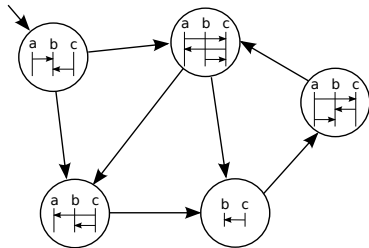
VASS are very close to Petri nets :

- A VASS can be simulated by a Petri net.
- A Petri net is a VASS with one state.



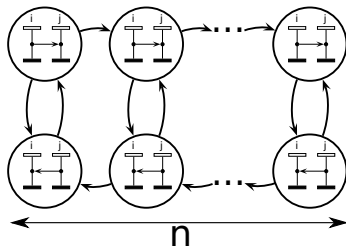
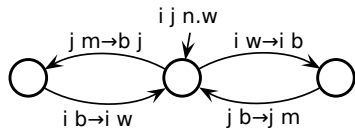
MSG (Message Sequence Graph)

Automaton where each node is labeled by an MSC.



- MSGs are a special case of VASSs.
- VASSs are exponentially more concise than MSGs.

Example : simplified sliding window protocol



Carstensen 87

Termination of a given VASS is EXPSPACE-hard.

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But, structural termination is polynomial problem.

Property

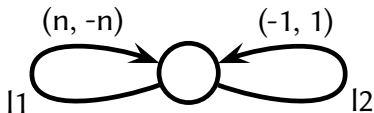
A VASS is structurally terminating if and only if there exists no closed path whose cost is $\geq \vec{0}$.

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Problem solvable in polynomial time by linear programming.

Minimum length of a closed path solution is potentially exponential.



$$l_1 \dots \underbrace{l_2 l_2 l_2 \dots}_{n \text{ times}} \Rightarrow l_1 + n \cdot l_2$$

- The counter example is a multiset of edges.

Challenge

The counter example as multiset of edge is too complex.

Goal

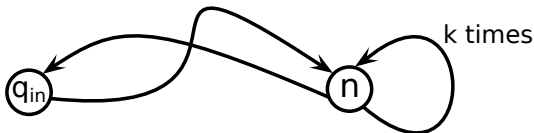
Find a simple representation of counter examples.

Solution

Use a set of lassos.

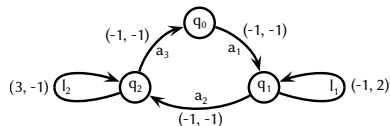
Definition

Let Y_0 be a circuit starting from node n . Let Y_1 be a simple path from q_{in} to n and Y_2 be a simple path from n to q_{in} . The closed path $Y_1 \cdot (Y_0)^k \cdot Y_2$ is called a **lasso with valuation k** starting from q_{in} .



Theorem

Let H be a closed path given as a multiset of edges. We can compute in polynomial time a finite multiset of lassos S starting from $b \in V_H$ such that $\text{cost}(S) = m \times \text{cost}(H)$ with $m \in \mathbb{N}^*$.

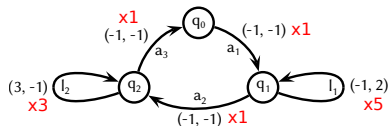


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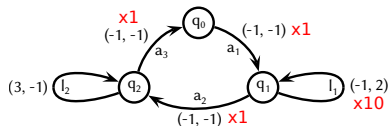
$$H = a_1 + 5l_1 + a_2 + 3l_2 + a_3$$



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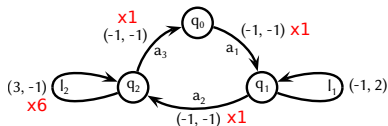
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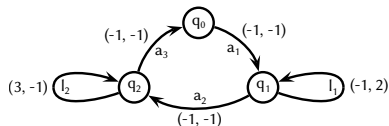
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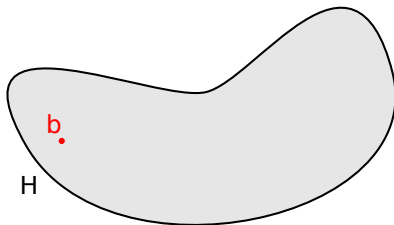
$$S = S_1 + S_2$$

$$\text{cost}(S) = 2 \times \text{cost}(H)$$

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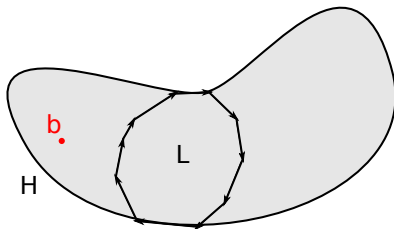
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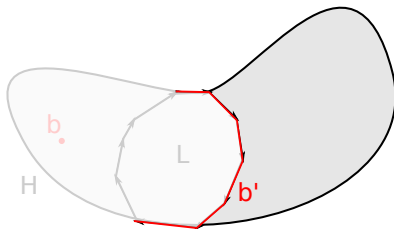
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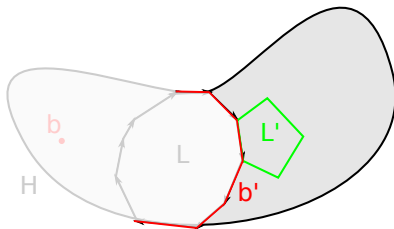
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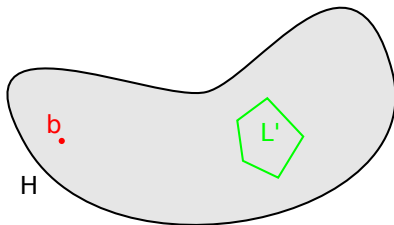
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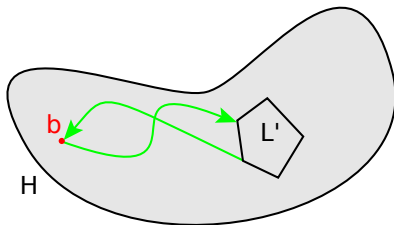
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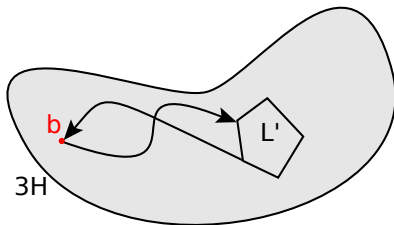
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Idea :



Corollary

Let H be a closed path with $b \in V_H$. Then there exist a closed path H' with almost d lassos starting from b such that $\text{cost}(H) = m \times \text{cost}(H')$.

Idea :

$$x_1 \cdot \text{cost}(S_1) + x_2 \cdot \text{cost}(S_2) + \dots + x_{|A|} \cdot \text{cost}(S_{|A|}) \geq \vec{0}$$

By linear programming, we can find d lassos such that

$$x_{i1} \cdot \text{cost}(S_{i1}) + x_{i2} \cdot \text{cost}(S_{i2}) + \dots + x_{id} \cdot \text{cost}(S_{id}) \geq \vec{0}$$

Conclusion

- Structural termination of VASS is equivalent to search a positive closed path.
- Linear programming solve this problem in polynomial time, but with complex counter example.
- Polynomial algorithm to represent a counter example by d lassos.

Thanks.