| Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|---------------------------------|----------------------------------|------------|
| 000000 | 0000 | |
| | | |

Runtime Enforcement of Timed Properties

Srinivas Pinisetty¹,Yliès Falcone², Thierry Jéron¹, Hervé Marchand¹, Antoine Rollet³ and Omer Nguena Timo³

> INRIA Rennes - Bretagne Atlantique, France LIG, Université Grenoble I, France LaBRI, Université de Bordeaux - CNRS, France

MOVEP 2012, December 05, Marseille

| Introduction | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|--------------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Outline | | | |



2 Enforcement of timed properties

3 Enforcement of safety properties

4 Conclusion

Introduction •00 nforcement of timed properties

Enforcement of safety properties 0000 Conclusion

Verification and enforcement monitors



- Does the run satisfy the property?
- Monitoring an executing system.
- No system model.
- Input: stream of events.
- Output: stream of verdicts.

Runtime enforcement

- The run should satisfy the property.
- Monitoring an executing system.
- No system model.
- Input: stream of events (may violate the property).
- Output: stream of events (should satisfy the property).

| Introductio | n |
|-------------|---|
| 000 | |

nforcement of timed properties

Enforcement of safety properties 0000

Verification and enforcement monitors



- Does the run satisfy the property?
- Monitoring an executing system.
- No system model.
- Input: stream of events.
- Output: stream of verdicts.

Runtime enforcement



- The run should satisfy the property.
- Monitoring an executing system.
- No system model.
- Input: stream of events (may violate the property).
- Output: stream of events (should satisfy the property).



- Possibly augmented with a memorization
- Possibly augmented with a memorization mechanism.



Enforcement mechanism

An EM modifies the current execution sequence (sometimes like a "filter").

- reads an input sequence $\sigma \in \Sigma^*$.
- outputs a new sequence $o \in \Sigma^*$.
- endowed with a set of enforcement primitives.
 - operates on the memorization mechanism.
 - delete or insert events using the memory content and the current input.

An EM behaves as a function $E: \Sigma^* \to \Sigma^*$.

| Introduction | 1 |
|--------------|---|
| 000 | |

Motivation for timed enforcement

Specifying the timing behavior

Allow specifying desired behavior of a system more precisely (time constraints between events).

• After an action "a", action "b" should occur with a delay of at least 5 time units between them.

- Domains: Real-time embedded systems, monitor hardware failures, communication protocols, web services and many more.
- Examples
 - Monitor a firewall to prevent DOS attack ensuring minimal delay between input events.
 - Monitor a web application to check if pre-conditions are met to provide a service.

| Introc | luction |
|--------|---------|
| 000 | |

Enforcement of safety properties 0000

Motivation for timed enforcement

Specifying the timing behavior

Allow specifying desired behavior of a system more precisely (time constraints between events).

• After an action "a", action "b" should occur with a delay of at least 5 time units between them.

- Domains: Real-time embedded systems, monitor hardware failures, communication protocols, web services and many more.
- Examples
 - Monitor a firewall to prevent DOS attack ensuring minimal delay between input events.
 - Monitor a web application to check if pre-conditions are met to provide a service.

| Introc | luction |
|--------|---------|
| 000 | |

Motivation for timed enforcement

Specifying the timing behavior

Allow specifying desired behavior of a system more precisely (time constraints between events).

• After an action "a", action "b" should occur with a delay of at least 5 time units between them.

- Domains: Real-time embedded systems, monitor hardware failures, communication protocols, web services and many more.
- Examples
 - Monitor a firewall to prevent DOS attack ensuring minimal delay between input events.
 - Monitor a web application to check if pre-conditions are met to provide a service.

| Introc | luction |
|--------|---------|
| 000 | |

Enforcement of safety properties 0000

Motivation for timed enforcement

Specifying the timing behavior

Allow specifying desired behavior of a system more precisely (time constraints between events).

• After an action "a", action "b" should occur with a delay of at least 5 time units between them.

- Domains: Real-time embedded systems, monitor hardware failures, communication protocols, web services and many more.
- Examples
 - Monitor a firewall to prevent DOS attack ensuring minimal delay between input events.
 - Monitor a web application to check if pre-conditions are met to provide a service.

| Introc | luction |
|--------|---------|
| 000 | |

Motivation for timed enforcement

Specifying the timing behavior

Allow specifying desired behavior of a system more precisely (time constraints between events).

• After an action "a", action "b" should occur with a delay of at least 5 time units between them.

- Domains: Real-time embedded systems, monitor hardware failures, communication protocols, web services and many more.
- Examples
 - Monitor a firewall to prevent DOS attack ensuring minimal delay between input events.
 - Monitor a web application to check if pre-conditions are met to provide a service.

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|---------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Outline | | | |



2 Enforcement of timed properties

3 Enforcement of safety properties

4 Conclusion

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|-------------|---------------------------------|----------------------------------|------------|
| | 00000 | | |
| Enforcement | of timed properties | | |

From untimed to timed properties enforcement

New elements have to be taken into account

• Input/output sequences are timed words:

$$\sigma = (\delta_1, a_1) \cdot (\delta_2, a_2) \cdots (\delta_n, a_n), \delta_i \in \mathbb{R}_{\geq}, a_i \in \Sigma.$$

• Property φ described by a timed automaton or a timed logic.

Synthesis of the corresponding enforcer?

• Class of enforceable properties?

- \rightarrow Focus on safety and co-safety properties modeled by TA.
- Model of the enforcer?
 - ightarrow Memory + similar operations (Store, Dump).
 - \rightarrow No finite structure.
 - \rightarrow Requirements (What should the enforcer do?).

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|-------------|---------------------------------|----------------------------------|------------|
| | 00000 | | |
| Enforcement | of timed properties | | |

From untimed to timed properties enforcement

New elements have to be taken into account

• Input/output sequences are timed words:

$$\sigma = (\delta_1, a_1) \cdot (\delta_2, a_2) \cdots (\delta_n, a_n), \delta_i \in \mathbb{R}_{\geq}, a_i \in \Sigma.$$

• Property φ described by a timed automaton or a timed logic.

Synthesis of the corresponding enforcer?

- Class of enforceable properties?
 - \rightarrow Focus on safety and co-safety properties modeled by TA.
- Model of the enforcer?
 - \rightarrow Memory + similar operations (Store, Dump).
 - \rightarrow No finite structure.
 - \rightarrow Requirements (What should the enforcer do?).

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|----------|---------------------------------|----------------------------------|------------|
| 000 | 00000 | 0000 | |
| Property | | | |

Defined by a timed language $\varphi \subseteq (\mathbb{R}_{\geq 0} \times \Sigma)^*$. A timed word σ satisfies φ (noted $\sigma \models \varphi$) if $\sigma \in \varphi$. Focus on properties specified by a TA \mathcal{A}_{φ} .

Safety and co-safety properties specified by TA

- Safety: nothing bad should ever happen (prefix closed).
- Co-safety: something good will eventually happen within a finite amount of time (extension closed).

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|----------|---------------------------------|----------------------------------|------------|
| 000 | 00000 | 0000 | |
| Property | | | |

Defined by a timed language $\varphi \subseteq (\mathbb{R}_{\geq 0} \times \Sigma)^*$. A timed word σ satisfies φ (noted $\sigma \models \varphi$) if $\sigma \in \varphi$. Focus on properties specified by a TA \mathcal{A}_{φ} .

Safety and co-safety properties specified by TA

- Safety: nothing bad should ever happen (prefix closed).
- Co-safety: something good will eventually happen within a finite amount of time (extension closed).

$$\Sigma_{1} \setminus \{r\} \qquad \Sigma_{1} \setminus \{r\} \qquad \Sigma_{1} \setminus \{r\} \qquad \Sigma_{1} \\ \uparrow \qquad r, \qquad r, \qquad 0 \qquad r, x < 5 \qquad 0 \\ \downarrow_{1} \qquad r, x \geq 5, \qquad r, x \geq 5, \\ x := 0 \qquad r = 0$$

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|----------|---------------------------------|----------------------------------|------------|
| 000 | 00000 | 0000 | |
| Property | | | |

Defined by a timed language $\varphi \subseteq (\mathbb{R}_{\geq 0} \times \Sigma)^*$. A timed word σ satisfies φ (noted $\sigma \models \varphi$) if $\sigma \in \varphi$. Focus on properties specified by a TA \mathcal{A}_{φ} .

Safety and co-safety properties specified by TA

- Safety: nothing bad should ever happen (prefix closed).
- Co-safety: something good will eventually happen within a finite amount of time (extension closed).



| Introduction | |
|--------------|--|
| | |

Enforcement of timed properties

Enforcement of safety properties 0000 Conclusior

Enforcement monitoring in a timed context



- φ : Property which should be enforced (specified by a TA).
- σ: Input timed word.
- Output at time t: $E(\sigma, t)$ should satisfy some additional constraints [Soundness, Transparency, Optimality].
- E realized as a Enforcement Monitor (EM).

| Introduction | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|--------------|---------------------------------|----------------------------------|------------|
| 000 | | 0000 | O |
| Enforcement | Monitor - EM | | |



Memory

Timed word

Operations

- Store: stores the received event and a delay in the memory.
- Dump: removes the event from memory and releases it as output.

| Introduction | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|--------------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Decisions | | | |

$$(\delta'_{1}, a_{1}) \cdots (\delta'_{k}, a_{k}) \models \varphi \xrightarrow{(\delta'_{k+1}, a_{k+1}) \cdots (\delta'_{m}, a_{m})} EM_{\varphi} \xrightarrow{\sigma = (\delta_{1}, a_{1}) \cdots (\delta_{k}, a_{k}) \cdots (\delta_{m}, a_{m}) \cdots (\delta_{n}, a_{n})} \xrightarrow{\sigma = (\delta_{1}, a_{1}) \cdots (\delta_{k}, a_{k}) \cdots (\delta_{m}, a_{m}) \cdots (\delta_{n}, a_{n})} \xrightarrow{\sigma = (\delta_{1}, a_{1}) \cdots (\delta_{k}, a_{k}) \cdots (\delta_{m}, a_{m}) \cdots (\delta_{n}, a_{n})} \xrightarrow{\sigma = (\delta_{1}, a_{1}) \cdots (\delta_{k}, a_{k}) \cdots (\delta_{m}, a_{m}) \cdots (\delta_{n}, a_{n})}$$

What can the enforcer do?

- No insertion, deletion of events.
- Order of events cannot be changed.
- Allow to increase the delay between actions.

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties | Conclusion O |
|---------------------|---------------------------------|----------------------------------|-----------------|
| Summary of | the approach | | |



- Requirements: Soundness, Transparency and Optimality conditions.
- Enforcement Monitor: Defined as a transition system (which should satisfy the requirements).
- Implementation: Translation of the EM semantic rules into algorithms.

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties | Conclusion O |
|---------------------|---------------------------------|----------------------------------|-----------------|
| Summary of | the approach | | |



- Requirements: Soundness, Transparency and Optimality conditions.
- Enforcement Monitor: Defined as a transition system (which should satisfy the requirements).
- Implementation: Translation of the EM semantic rules into algorithms.

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties | Conclusion O |
|---------------------|---------------------------------|----------------------------------|-----------------|
| Summary of | the approach | | |



- Requirements: Soundness, Transparency and Optimality conditions.
- Enforcement Monitor: Defined as a transition system (which should satisfy the requirements).
- Implementation: Translation of the EM semantic rules into algorithms.

| Introduction | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|--------------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Outline | | | |

1 Introduction

2 Enforcement of timed properties

Inforcement of safety properties

4 Conclusion

| Introd | |
|--------|--|
| | |

Inforcement of timed properties

Enforcement of safety properties

Enforcement of a safety property

oundness

$\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, \ E(\sigma, t) \models \varphi.$

At any time instant t, the output $E(\sigma, t)$ delays the input $\operatorname{obs}(\sigma, t)$: $\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \preccurlyeq_d \operatorname{obs}(\sigma, t) \land \operatorname{time}(E(\sigma, t)) \leq t.$

If E is sound and transparent, it is *optimal* for any σ , t if

- (Op1) E(σ, t) is among the longest correct timed words delaying obs(σ, t).
- (Op2) Every prefix of $E(\sigma, t)$ has the shortest possible last delay.

| Introd | |
|--------|--|
| | |

Inforcement of timed properties

Enforcement of safety properties

Enforcement of a safety property

Soundness

$\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \models \varphi.$

ransparency

At any time instant t, the output $E(\sigma, t)$ delays the input $\operatorname{obs}(\sigma, t)$: $\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \preccurlyeq_d \operatorname{obs}(\sigma, t) \land \operatorname{time}(E(\sigma, t)) \leq t.$

If *E* is sound and transparent, it is *optimal* for any σ , *t* if

- (Op1) $E(\sigma, t)$ is among the longest correct timed words delaying $obs(\sigma, t)$.
- (Op2) Every prefix of $E(\sigma, t)$ has the shortest possible last delay.

| Introd | |
|--------|--|
| | |

inforcement of timed properties

Enforcement of safety properties

Enforcement of a safety property

Soundness

$\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \models \varphi.$

ransparency

At any time instant t, the output $E(\sigma, t)$ delays the input $\operatorname{obs}(\sigma, t)$: $\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \preccurlyeq_d \operatorname{obs}(\sigma, t) \land \operatorname{time}(E(\sigma, t)) \leq t.$

If *E* is sound and transparent, it is *optimal* for any σ , *t* if

- (Op1) E(σ, t) is among the longest correct timed words delaying obs(σ, t).
- (Op2) Every prefix of $E(\sigma, t)$ has the shortest possible last delay.

| | od | | |
|----|----|--|--|
| 00 | | | |

Enforcement of timed properties

Enforcement of safety properties

Enforcement of a safety property

Soundness

$$\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \models \varphi.$$

ransparency

At any time instant t, the output $E(\sigma, t)$ delays the input $\operatorname{obs}(\sigma, t)$: $\forall \sigma \in (\mathbb{R}_{\geq 0} \times \Sigma)^*, \forall t \in \mathbb{R}_{\geq 0}, E(\sigma, t) \preccurlyeq_d \operatorname{obs}(\sigma, t) \land \operatorname{time}(E(\sigma, t)) \leq t.$

Optimality

- If E is sound and transparent, it is *optimal* for any σ , t if
 - (Op1) $E(\sigma, t)$ is among the longest correct timed words delaying $obs(\sigma, t)$.
 - (Op2) Every prefix of $E(\sigma, t)$ has the shortest possible last delay.

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|----------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| EM for a | safety property | | |

$$\textit{EM} = \langle \textit{C},\textit{C}_0,\, \Gamma_{\textit{EM}}, \hookrightarrow \rangle$$

- $C = (\mathbb{R}_{\geq 0} \times \Sigma)^* \times \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \times \mathbb{B} \times Q$ is the set of configurations
- Initial configuration is $C_0 = \langle \epsilon, 0, 0, \mathtt{tt}, q_0 \rangle \in C;$
- Γ_{EM} = ((ℝ_{≥0} × Σ) ∪ {ε}) × Op × ((ℝ_{≥0} × Σ) ∪ {ε}) is the input-operation-output alphabet, where Op = {Store(·), Dump(·), Delay(·)};

•
$$\hookrightarrow \subseteq C \times \Gamma_{EM} \times C$$

EM should fulfill the soundness, transparency and optimality conditions.

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|------------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Operations | | | |

1. Store

$$\langle \sigma_s, \delta, d, \mathtt{tt}, q \rangle \stackrel{(\delta, \mathbf{a})/\mathrm{Store}(\delta', \mathbf{a})/\epsilon}{\hookrightarrow} \langle \sigma_s \cdot (\delta', \mathbf{a}), 0, d, (\delta' \neq \infty), q' \rangle \text{ with:}$$

•
$$\delta' = ext{shortest delay } \delta' \geq \delta ext{ s.t. } (q \stackrel{(\delta', a)}{\to} q', q' \in G)$$

•
$$q'$$
 is defined as $q \stackrel{(\delta', \mathsf{a})}{ o} q'$ if $\delta' < \infty$ and $q' = q$ otherwise

2. Dump

$$\left\langle \left(\delta, \boldsymbol{a}\right) \cdot \sigma_{\boldsymbol{s}}, \boldsymbol{s}, \delta, \boldsymbol{b}, \boldsymbol{q} \right\rangle \overset{\epsilon/\operatorname{Dump}\left(\delta, \boldsymbol{a}\right)/\left(\delta, \boldsymbol{a}\right)}{\hookrightarrow} \left\langle \sigma_{\boldsymbol{s}}, \boldsymbol{s}, \boldsymbol{0}, \boldsymbol{b}, \boldsymbol{q} \right\rangle \text{ if } \delta \neq \infty$$

3. Delay

$$\langle \sigma_{\mathfrak{s}}, \mathfrak{s}, \mathfrak{d}, \mathfrak{b}, \mathfrak{q} \rangle \stackrel{\epsilon/\operatorname{del}(\delta)/\epsilon}{\hookrightarrow} \langle \sigma_{\mathfrak{s}}, \mathfrak{s} + \delta, \mathfrak{d} + \delta, \mathfrak{b}, \mathfrak{q} \rangle$$

| Implemen | ntation | | |
|--------------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Introduction | Enforcement of timed properties | Enforcement of safety properties | Conclusion |



Algorithm: StoreProcess $(l, X) \leftarrow (l_{\text{init}}, [X \leftarrow 0])$ while tt do $(\delta, a) \leftarrow \text{await } event$ if $(post(l, X, a, \delta) \notin G)$ then $\delta' \leftarrow \text{update}(l, X, a, \delta)$ if $\delta' = \infty$ then terminate StoreProcess end if else $\delta' \leftarrow \delta$ end if $(l, X) \leftarrow \text{post}(l, X, a, \delta')$ enqueue (δ', a) end while

```
\label{eq:linear_states} \begin{array}{c} \hline \text{Algorithm: DumpProcess} \\ \hline d \leftarrow 0 \\ \textbf{while tt do} \\ await (|\sigma_s| \geq 1) \\ (\delta, a) \leftarrow \text{dequeue } (\sigma_s) \\ wait (\delta - d) \\ \text{dump } (a) \\ d \leftarrow 0 \\ \textbf{end while} \end{array}
```

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|---------|---------------------------------|----------------------------------|------------|
| 000 | 000000 | 0000 | |
| Outline | | | |

1 Introduction

2 Enforcement of timed properties

3 Enforcement of safety properties

4 Conclusion

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|------------|---------------------------------|----------------------------------|------------|
| | | | • |
| Conclusion | | | |

Formal approach for enforcing timed properties

- Enforcer adds additional delay between input actions in order to satisfy the property.
- Additional constraints to ensure choosing "best" delay between actions.
- Focused on safety/co-safety properties.
- Algorithms to implement the enforcers.
- Prototypes developed using Python and UPPAAL.

Ongoing/ future work

- Enforcing more expressive properties.
- New transparency conditions.
- Improve implementation.
- Test on case studies (analysis, different architectures).

| | Enforcement of timed properties | Enforcement of safety properties | Conclusion |
|------------|---------------------------------|----------------------------------|------------|
| | | | • |
| Conclusion | | | |

Formal approach for enforcing timed properties

- Enforcer adds additional delay between input actions in order to satisfy the property.
- Additional constraints to ensure choosing "best" delay between actions.
- Focused on safety/co-safety properties.
- Algorithms to implement the enforcers.
- Prototypes developed using Python and UPPAAL.

Ongoing/ future work

- Enforcing more expressive properties.
- New transparency conditions.
- Improve implementation.
- Test on case studies (analysis, different architectures).

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties 0000 | Conclusion O |
|---------------------|--|--|-----------------|
| Example | | | |
| | $ \begin{array}{c} \Sigma_1 \setminus \{r\} & \Sigma_1 \setminus \{r\} \\ & & & \\ & $ | $(r, x < 5) \xrightarrow{\Sigma_1} (l_2)$ $(3, r) \cdot (1, r)$ | |
| <i>t</i> ≏ 0 | $\frac{\epsilon}{\epsilon} (\epsilon, 0, 0, \mathtt{tt}, < l_0, 0 >)/(1, a) \cdot (3, r) \cdot (1, r)$ $\downarrow del(1)$ | | |
| t = 1 | $\epsilon/(\epsilon, 1, 1, tt, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)$ \downarrow Store | | |
| | | | |
| | | | |
| | | | |
| | | | |

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties | Conclusion O |
|---------------------|--|--|-----------------|
| Example | | | |
| | $\Sigma_1 \setminus \{r\} \qquad \Sigma_1 \setminus \{r\}$ $\downarrow r, \qquad \Sigma_1 \setminus \{r\}$ $\downarrow r, \qquad r, \qquad \downarrow r, \qquad r, \qquad$ | $\xrightarrow{\Sigma_1} \underbrace{\bigcirc}_{l_2} \\ 3, r) \cdot (1, r)$ | |
| <i>t</i> ≏ 0 | $\epsilon/(\epsilon, 0, 0, \mathtt{tt}, < l_0, 0 >)/(1, a) \cdot (3, r) \cdot (1, r) \ \downarrow \mathrm{del}(1)$ | | |
| t = 1 | $\epsilon/(\epsilon, 1, 1, tt, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)$ \downarrow Store | | |
| t = 1 | $\epsilon/((1,a),0,1,\mathtt{tt},<\mathit{l}_0,1>)/(3,r)\cdot(1,r)$ $\downarrow Dump$ | | |
| | | | |
| | | | |
| | | | |

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties 0000 | Conclusion O |
|---------------------|--|--|-----------------|
| Example | | | |
| | $\Sigma_1 \setminus \{r\} \qquad \Sigma_1 \setminus \{r\}$ $\downarrow i_0 \qquad x := 0 \qquad \downarrow i_1 \qquad f$ $\uparrow \qquad f$ $r, x \ge 5, \\ x := 0$ Input $\sigma = (1, a) \cdot ($ | $(x, x < 5) \xrightarrow{\Sigma_1} l_2$ $(3, r) \cdot (1, r)$ | |
| $t \triangleq 0$ | $\epsilon/(\epsilon, 0, 0, tt, < l_0, 0 >)/(1, a) \cdot (3, r) \cdot (1, r)$ del(1) | | |
| t = 1 | $\epsilon/(\epsilon, 1, 1, tt, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)$ \downarrow Store | | |
| t = 1 | $\epsilon/((1,a),0,1,tt,< l_0,1>)/(3,r) \cdot (1,r)$ $\downarrow Dump$ | | |
| t = 1 | $(1,a)/(\epsilon,0,0,\mathtt{tt},<\mathit{l}_0,1>)/(3,r)\cdot(1,r)\ \downarrow \mathrm{del}(3)$ | | |
| | | | |
| | | | |

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties | Conclusion O |
|---------------------|---|---|---------------------|
| Example | | | |
| | $ \begin{array}{c} \Sigma_1 \setminus \{r\} & \Sigma_1 \setminus \{r\} \\ \hline \\ l_0 & x := 0 \\ \uparrow & & \downarrow \\ r, x \ge 5, \\ x := 0 \\ \end{array} \\ \\ Input \ \sigma = (1, \mathbf{a}) \cdot ($ | $ \xrightarrow{\Sigma_1} \underbrace{\bigcirc}_{l_2} \\ 3, r) \cdot (1, r) $ | |
| $t \triangleq 0$ | $\epsilon/(\epsilon, 0, 0, tt, < I_0, 0 >)/(1, a) \cdot (3, r) \cdot (1, r)$ | $ (1, a) \cdot (3, r) / (\epsilon, 0, 0; tt, < l_1, 0 >) / (1) $ | $,r) t \simeq 4$ |
| t = 1 | $\frac{\epsilon}{(\epsilon, 1, 1, \mathtt{tt}, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)} \downarrow \text{Store}$ | $(1, a) \cdot (3, r)/(\epsilon, 1, 1, tt, < l_1, 1 >)/(1 \downarrow Store$ | (r) t = 5 |
| t = 1 | $\frac{\epsilon}{((1,a),0,1,\texttt{tt},< l_0,1>)/(3,r)\cdot(1,r)}{\downarrow Dump}$ | $(1, a) \cdot (3, r) / ((5, r), 0, 1, tt, < l_1, 0 > $ $\downarrow del(4)$ | $)/\epsilon$ $t=5$ |
| t = 1 | $(1,a)/(\epsilon,0,0,\texttt{tt},< l_0,1>)/(3,r)\cdot(1,r)$ $\downarrow del(3)$ | $(1, a) \cdot (3, r) / ((5, r), 4, 5, tt, < l_1, 4 > $ $\downarrow Dump$ | $)/\epsilon$ $t=9$ |
| t = 4 | $(1,a)/(\epsilon,3,3,tt,< l_0,4>)/(3,r)\cdot(1,r)$ $\downarrow \text{Store}$ | $(1, a) \cdot (3, r) \cdot (5, r)/(\epsilon, 4, 0, tt, < l_1, 4 > $ Dump | $>)/\epsilon t = 9$ |
| t = 4 | $(1,a)/((3,r),0,3,tt,< l_1,0>)/(1,r)$ — | | |

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties 0000 | Conclusion O |
|---------------------|---|--|--------------------------------|
| Example | | | |
| | $\Sigma_1 \setminus \{r\} \qquad \Sigma_1 \setminus \{r\}$ $\downarrow r, \qquad \Sigma_1 \setminus \{r\}$ $\downarrow r, \qquad r, \qquad \downarrow r, \qquad r, \qquad$ | $(x < 5) \xrightarrow{\Sigma_1} (l_2)$ $(3, r) \cdot (1, r)$ | |
| <i>t</i> ≏ 0 | $\frac{\epsilon}{(\epsilon,0,0,\mathtt{tt},)/(1,a)\cdot(3,r)\cdot(1,r)} \\ \downarrow \operatorname{del}(1)$ | $\rightarrow (1, a) \cdot (3, r) / (\epsilon, 0, 0; tt, < l_1, 0 >) / (1,]$ | <i>r</i>) <i>t</i> ≏ 4 |
| t = 1 | $\frac{\epsilon}{(\epsilon, 1, 1, \texttt{tt}, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)} \downarrow \text{Store}$ | $(1, a) \cdot (3, r) / (\epsilon, 1, 1, tt, < l_1, 1 >) / (1, \downarrow Store$ | <i>r</i>) <i>t</i> = 5 |
| t = 1 | $\frac{\epsilon}{((1,a),0,1,\texttt{tt},<\textit{l}_0,1>)/(3,r)\cdot(1,r)} \downarrow Dump$ | $(1, a) \cdot (3, r)/((5, r), 0, 1, tt, < l_1, 0 >)$ $\downarrow del(4)$ | $\epsilon t = 5$ |
| t = 1 | $(1,a)/(\epsilon,0,0,\mathtt{tt},< l_0,1>)/(3,r)\cdot(1,r) \ \downarrow del(3)$ | $(1, a) \cdot (3, r) / ((5, r), 4, 5, tt, < l_1, 4 >)$ $\downarrow Dump$ | t = 9 |
| t = 4 | $(1, a)/(\epsilon, 3, 3, tt, < l_0, 4 >)/(3, r) \cdot (1, r)$ \$\frac{1}{5} Store | $(1, a) \cdot (3, r) \cdot (5, r) / (\epsilon, 4, 0, tt, < l_1, 4 > Dump$ | $(\cdot)/\epsilon t = 9$ |
| t = 4 | $(1,a)/((3,r),0,3,tt,< l_1,0>)/(1,r)$ — |] | |

| Introduction 000 | Enforcement of timed properties | Enforcement of safety properties 0000 | Conclusion O |
|---|--|--|--------------------------|
| Example | | | |
| $\sum_{1} \setminus \{r\} \qquad \sum_{1} \setminus \{r\} \qquad \sum_{1} \setminus \{r\} \qquad \sum_{1} \setminus \{r\} \qquad \sum_{1} \cap \{r, x < 5\} \qquad 0$ $\uparrow \qquad \qquad$ | | | |
| $t \doteq 0$ | $\frac{\epsilon}{(\epsilon,0,0,\mathtt{tt},<\mathit{l}_0,0>)/(1,a)\cdot(3,r)\cdot(1,r)} \\ \downarrow \mathrm{del}(1)$ | $\xrightarrow{(1, a) \cdot (3, r)/(\epsilon, 0, 0; tt, < l_1, 0 >)/(1, \ del(1))}$ | r) t ≏ 4 |
| t = 1 | $\epsilon/(\epsilon, 1, 1, tt, < l_0, 1 >)/(1, a) \cdot (3, r) \cdot (1, r)$ \$\store\$ | $(1, a) \cdot (3, r) / (\epsilon, 1, 1, tt, < l_1, 1 >) / (1, \downarrow Store$ | <i>r</i>) <i>t</i> = 5 |
| t = 1 | $\frac{\epsilon}{((1,a),0,1,\mathtt{tt},< l_0,1>)/(3,r)\cdot(1,r)} \downarrow Dump$ | $(1,a) \cdot (3,r)/((5,r),0,1,tt,< l_1,0>)$ $\downarrow del(4)$ | $\epsilon t = 5$ |
| t = 1 | $(1,a)/(\epsilon,0,0,\mathtt{tt},< l_0,1>)/(3,r)\cdot(1,r) \ \downarrow del(3)$ | $(1,a) \cdot (3,r)/((5,r),4,5,\texttt{tt},< l_1,4>) \\ \downarrow Dump$ | $\epsilon t = 9$ |
| t = 4 | $(1, a)/(\epsilon, 3, 3, tt, < l_0, 4 >)/(3, r) \cdot (1, r)$ \$\store\$ | $(1, a) \cdot (3, r) \cdot (5, r) / (\epsilon, 4, 0, tt, < l_1, 4 >$ Dump | $(\cdot)/\epsilon t = 9$ |
| t = 4 | $(1,a)/((3,r),0,3,tt,< l_1,0>)/(1,r)$ |] | |